

# On Robustness of Average Inflation Targeting

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\*The views expressed in this presentation are the authors' views and not the views of the Bank of Finland or the Eurosystem

# Motivation

- ▶ In August 2020, Fed announces new policy framework of average inflation targeting (AIT).

Powell (2020): *“We will seek to achieve inflation that averages 2 percent over time. ... when inflation has been running below 2 percent, appropriate monetary policy will likely aim to achieve inflation moderately above 2 percent for some time.”*

- ▶ Several papers studied AIT under RE.
  - ▶ RE is restrictive, especially in times that are outside “normal”.
  - ▶ Bounded rationality (Budianto et al. 2020); rule-of-thumb (Amano et al. 2020).
  - ▶ Expectations and AIT (Coibion et al. 2020; Salle, 2021).
- ▶ **Question:** How does AIT perform if there is imperfect knowledge and private agents engage in learning to forecast future?

# Preview of Results

Our analysis raises **warning signals** concerning robustness of AIT under conditions of imperfect knowledge:

1. Target equilibrium can be locally unstable under learning.
2. Standard IT policy may outperform AIT at the zero lower bound (ZLB).

Policy Implications:

1. Good communication and weighted average inflation targeting can improve some outcomes.
2. Symmetry matters.
3. We need to think carefully about policy rules.

## Example 1: Fisherian Model

- ▶ Consider the Fisher relation:

$$\hat{R}_t = \beta^{-1} \hat{\pi}_t^e$$

- ▶  $\hat{R}_t$  is the nominal interest rate,  $\beta$  is the subjective discount rate.
- ▶  $\hat{\pi}_t^e$  is the expected inflation rate  $\hat{\pi}_{t+1}$  in period  $t + 1$  and formed in period  $t$ .

## Example 1: Fisherian Model

- ▶ **AIT monetary policy:** nominal interest rate is set in response to an average of deviations from inflation target  $\pi^*$ . Linearization around the steady state with  $\pi^*$  is

$$\hat{R}_t = \frac{\psi}{\pi^*} \sum_{k=0}^{L-1} \hat{\pi}_{t-k}.$$

- ▶ **Assumptions:**
  1.  $\pi^* < \beta\psi$  (**Taylor principle**).
  2. Private agents do not know any details of policy rule (**Opacity**).

## Example 1: Fisherian Model

- ▶ With opacity about monetary policy, private agents forecast inflation using a simple weighted average of past inflation (steady state learning with constant gain)

$$\hat{\pi}_t^e = \hat{\pi}_{t-1}^e + \omega(\hat{\pi}_{t-1} - \hat{\pi}_{t-1}^e),$$

where  $\omega > 0$  is small.

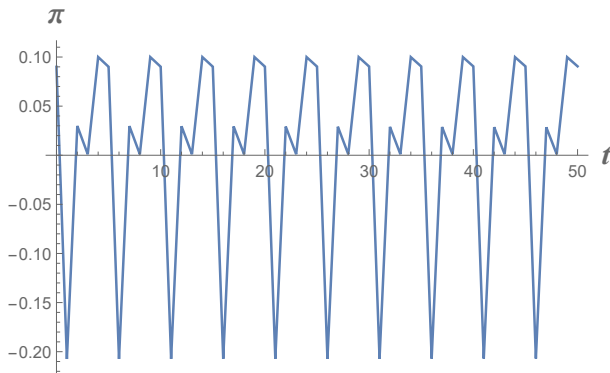
- ▶ Temporary equilibrium relation:

$$\hat{\pi}_t = \frac{\pi^*}{\beta\psi} \hat{\pi}_t^e - \sum_{i=1}^{L-1} \hat{\pi}_{t-i}.$$

**Remark:** Assume that  $\pi^* < \beta\psi$ . The steady state  $\pi^*$  is locally stable under the above system if  $L \leq 3$  but is explosive if  $L = 4$  and for many higher values of  $L$ .

## Example 1: Fisherian Model

- ▶ Numerical example:  $L = 4$  and  $\pi^* = 1.005$ ,  $\beta = 0.99$ ,  $\psi = 1.5$  and  $\omega = 0.001$ .



# Example 1: Fisherian Model

## What drives instability under AIT?

1. **Makeup:** inflation overshoots after period of undershooting.
2. **Finite data window** (“bygones are bygones”) → pattern of over-/undershooting.
3. **Opacity:** long-term expectations drift.

We have stability under price level targeting and traditional inflation targeting.



## Example 2: New Keynesian Model

- ▶ Log-linearized model with Euler equation learning:

$$\hat{y}_t = \hat{y}_t^e - \sigma(\hat{R}_t - \hat{\pi}_t^e)$$

$$\hat{\pi}_t = \beta\hat{\pi}_t^e + \kappa\hat{y}_t$$

$$\hat{R}_t = \psi \sum_{k=0}^{L-1} \hat{\pi}_{t-k}.$$

where  $\hat{y}$  is the output gap.  $\kappa$  is decreasing in price rigidity.

- ▶ Steady state learning with constant gain:

$$\hat{\pi}_t^e = \hat{\pi}_{t-1}^e + \omega(\hat{\pi}_{t-1} - \hat{\pi}_{t-1}^e)$$

$$\hat{y}_t^e = \frac{1-\beta}{\kappa} \hat{\pi}_t^e$$

## Example 2: New Keynesian Model

- ▶ Temporary equilibrium relation is

$$\hat{\pi}_t = \frac{\kappa^{-1} + \sigma}{\kappa^{-1} + \sigma\psi} \hat{\pi}_t^e - \frac{\sigma\psi}{\kappa^{-1} + \sigma\psi} \sum_{k=1}^{L-1} \hat{\pi}_{t-k}.$$

Flexibility as  $\kappa \rightarrow \infty$  then instability.

- ▶ For any  $\kappa$

$$\hat{\pi}_t = \frac{1 - \kappa\sigma\omega(\psi - 1)}{\kappa\sigma\psi + 1} \hat{\pi}_{t-1} - \frac{\omega\kappa\sigma\psi}{1 + \kappa\sigma\psi} \sum_{k=2}^L \hat{\pi}_{t-k} + \frac{\kappa\sigma\psi(1 - \omega)}{\kappa\sigma\psi + 1} \hat{\pi}_{t-L}.$$

- When prices are very sticky ( $\kappa$  is small), small  $\omega$

$$\hat{\pi}_t \approx A \hat{\pi}_{t-1}$$

with  $A$  slightly smaller than 1 (given small  $\omega$ ).

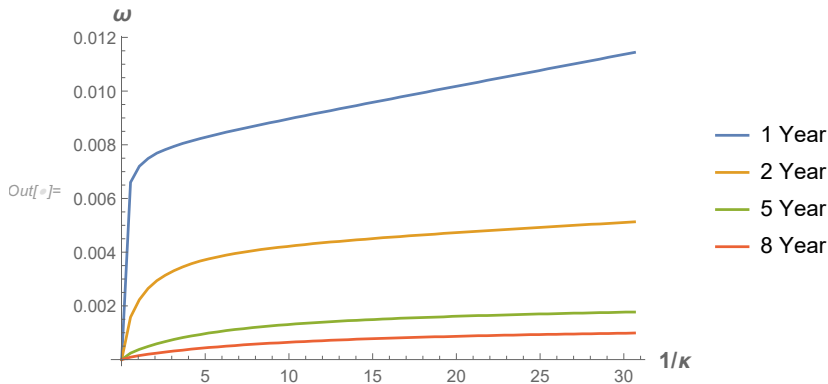
# Formal Analysis

We develop a non-linear New Keynesian model with infinite horizon learning agents and AIT and investigate the following:

1. Stability of the target equilibrium under constant-gain learning with opacity.
2. The importance of discounting past inflation data.
3. The importance of communication near the target and at the ZLB.
4. The importance of symmetry.

# #1. Stability of the Target Equilibrium

- ▶ Flexible prices  $\implies$  instability of target equilibrium for  $L \geq 4$ .
- ▶ With sticky prices, target is not **robustly stable**.



- ▶ Estimates of gain parameter:  $\omega \in [.002, .04]$ .

## #2. Weighted Average Inflation Targeting

1. A discounted average inflation target modestly improves stability outcomes:

$$R_t \equiv 1 + \max[\bar{R} - 1 + \psi_p \left[ \sum_{i=0}^{L-1} \mu^i \left( \frac{\pi_{t-i}}{\pi^*} - 1 \right) \right] + \psi_y \left[ \frac{y_t}{y^*} - 1 \right], 0],$$

where  $0 < \mu < 1$ .

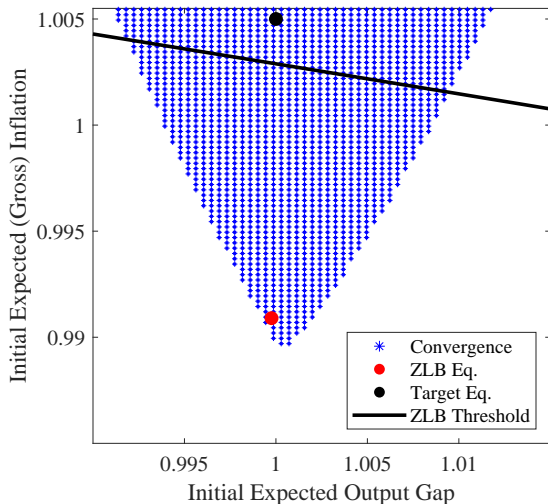
2. An exponential moving average inflation target may destabilize expectations:

$$R_t = 1 + \max[\bar{R} - 1 + \psi_p \left( \frac{\pi_t^{w_c} (\pi_t^{cb})^{1-w_c}}{\pi^*} - 1 \right), 0]$$
$$\pi_t^{cb} = \pi_{t-1}^{w_c} (\pi_{t-1}^{cb})^{1-w_c}$$

where  $0 < w_c < 1$ .

### #3. Importance of Communication

- ▶ If agents understand  $L$ , then the target is more robustly stable.
- ▶ At ZLB, traditional inflation targeting is about as effective.



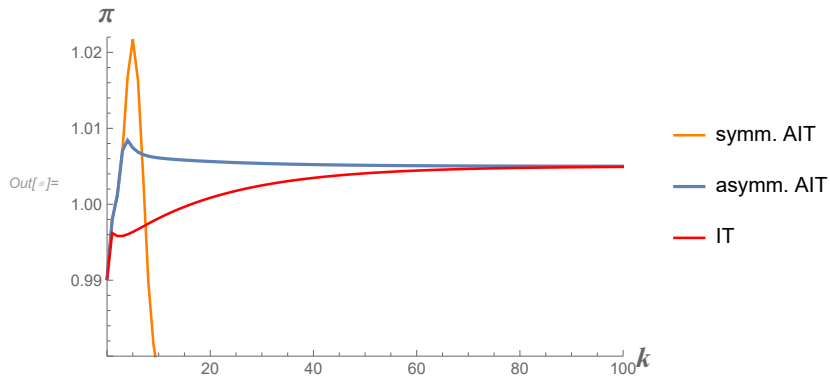
## #4. Symmetry vs. Asymmetry

- ▶ Consider the following asymmetric AIT rule;

$$R_t = 1 + \max[\bar{R} - 1 + \psi_p[\mathcal{P}_t - 1] + \psi_y[(y_t - y^*)/y^*], 0],$$
$$\mathcal{P}_t = \begin{cases} \prod_{i=0}^{L-1} (\pi_{t-i}/\pi^*) & \text{if } \prod_{i=1}^L \pi_{t-i} < (\underline{\pi})^L \\ \pi_t/\pi^* & \text{if } \prod_{i=1}^L \pi_{t-i} \geq (\underline{\pi})^L, \end{cases}$$

- ▶  $\underline{\pi} < \pi^* \implies$  robust stability under asymmetric AIT rules.

# Escaping the ZLB





# Conclusion

- ▶ Policymakers should be cautious when implementing AIT.
- ▶ Stability of target steady state under learning is not robust.
- ▶ Structural information to private agents, discounting older data, or asymmetric rules are useful to mitigate the problem.
- ▶ **Extensions:**
  - Imperfect and evolving credibility after new regime is introduced.
  - Asymmetric and switching rules.